



## **Myomo to Present at Sidoti & Company Virtual Microcap Conference**

**CAMBRIDGE, Mass. (November 18, 2020) – Myomo, Inc. (NYSE American: MYO)** (“Myomo” or the “Company”), a wearable medical robotics company that offers increased functionality for those suffering from neurological disorders and upper-limb paralysis, today announced that management will be presenting at the Sidoti & Company Virtual Microcap Conference on Thursday, November 19, 2020 at 1:45 p.m. Eastern Time.

The presentation will be webcast live and available for replay in the Investor Relations section of the Company’s [website](#) or [here](#).

### **About Myomo**

Myomo, Inc. is a wearable medical robotics company that offers improved arm and hand function for those suffering from neurological disorders and upper-limb paralysis. Myomo develops and markets the MyoPro product line. MyoPro is a powered upper-limb orthosis designed to support the arm and restore function to the weakened or paralyzed arms of certain patients suffering from CVA stroke, brachial plexus injury, traumatic brain or spinal cord injury, ALS or other neuromuscular disease or injury. It is currently the only marketed device that, sensing a patient’s own EMG signals through non-invasive sensors on the arm, can restore an individual’s ability to perform activities of daily living, including feeding themselves, carrying objects and doing household tasks. Many are able to return to work, live independently and reduce their cost of care. Myomo is headquartered in Cambridge, Massachusetts, with sales and clinical professionals across the U.S. and representatives internationally. For more information, please visit [www.myomo.com](http://www.myomo.com).

### **Contacts:**

For Myomo:  
[ir@myomo.com](mailto:ir@myomo.com)

Investor Relations:  
Kim Sutton Golodetz  
LHA Investor Relations  
[kgolodetz@lhai.com](mailto:kgolodetz@lhai.com)  
212-838-3777

Public Relations:  
Kate McCann  
Matter Communications  
[myomo@matternow.com](mailto:myomo@matternow.com)